

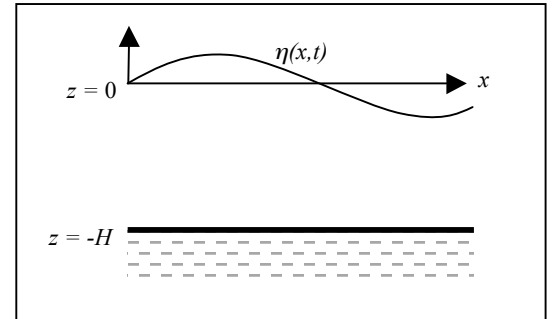
# Surface Waves

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## 1. Governing equations

Linear wave theory – small amplitude assumption

$$\text{Solve: } \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial z^2} = 0 \text{ subject to } \begin{cases} \frac{\partial \phi}{\partial z} = \frac{\partial \eta}{\partial t} \text{ at } z = 0 \\ \frac{\partial \phi}{\partial z} = 0 \text{ at } z = -H \\ \frac{\partial \phi}{\partial t} = -g\eta \text{ at } z = 0 \end{cases}$$



$$\text{Solution: } \phi(x, z, t) = \frac{a\omega}{k} \frac{\cosh k(z + H)}{\sinh kH} \sin(kx - \omega t)$$

## 2. Dispersion relationship

$$\omega^2 = gk \tanh kH$$

Deep water:  $kH \gg 1$ ;  $\omega^2 = gk$ ;  $c_p = 2c_g$       Waves are dispersive

Shallow water:  $kH \ll 1$ ;  $\omega^2 = gHk^2$ ;  $c_p = c_g$       Waves are non-dispersive

## 3. Basic definitions

Wave spectrum:  $F(f, \theta)$  used to characterise sea-surface elevation

$$\begin{aligned} \text{Significant Wave Height: } H_s &= 4\sqrt{F(f, \theta)} \\ &= \text{average value of the } \frac{1}{3} \text{ highest waves in a sample} \end{aligned}$$

## 4. Operational wave modelling

WAM, WAVEWATCH III<sup>TM</sup>, SWAN

$$\frac{\partial F}{\partial t} + \nabla \cdot (\mathbf{c}_g F) = S_{in} + S_{nl} + S_{ds} + S_{bot}$$

Typical *rms* error for short-range forecasts from global scale wave models is ~0.5 m.

## 5. References

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