

Data Assimilation for the Bureau's Operational Systems:

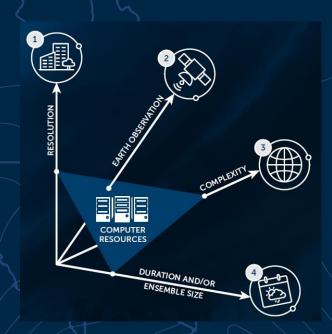
**Aims and Challenges** 

Peter Steinle, Bureau of Meteorology



## Context

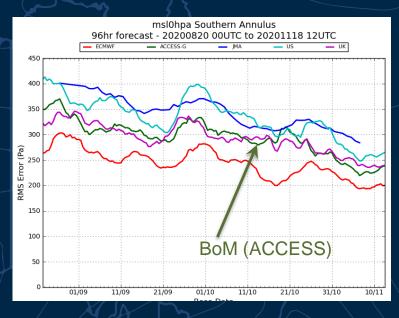
- R&D Plan for 2020-2030
- Better rapid update, km-scale DA (clouds, PBL etc.)
- Pathway to Coupled DA
- Pathway to Urban Scale
- Atmospheric DA requires
  - wide range of scales to be initialized: 4D Var + Ensembles
  - More satellites, radar etc.
- Evolving environment
  - Changes in models (UM → LFRic, MORUSES, ...)
  - New HPC architecture
  - New sources of observations





## Where are we now?

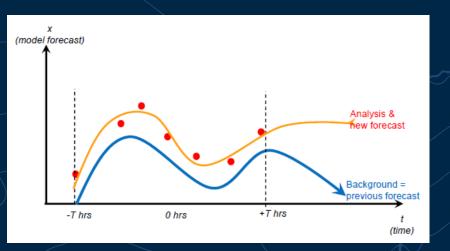
- Global NWP (12km/30km):
  - Hybrid 4DVar
- km-scale NWP (1.5km/2.2km):
  - 4D-Var + Latent Heat Nudging (& radar reflectivity)
- Land Surface: EKF for soil temperature & moisture
- Ocean: EnKF-C
- Sea Ice: Nil
- Ocean Waves: Nil
- Network Design / Value of Observations: FSOI



96hr RMS Forecast Error, MSLP 60°S-20°S (lower is better)



## 4DVar



#### Compare obs & background

- Adjoint model maps obs differences back to initial state
- Perturb initial condition & forecast, given known error characteristics
- Repeat

#### Linear Perturbation Model & Adjoint link time

- Very simple for UM (no convection etc.)
- Defines analysis variables (total moisture)

#### Background error covariance fill the gap between obs

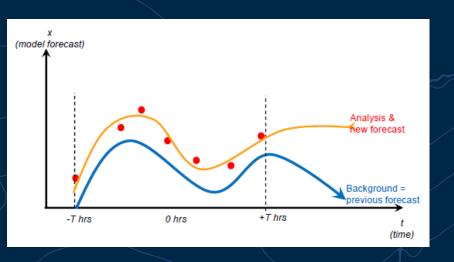
- Need ensemble info as vary in space, time & shape
- But ensemble is very small
  - $\rightarrow$  use  $\mathbf{B}_{\mathbf{c}}$  (climatological)

Ensemble just provides local modifications

= Hybrid VAR



## 4DVar & ensembles



# **Two Options**

#### EnVar:

- use non-linear solutions (ensemble)
- Increments from  $\boldsymbol{B_c}$  do not evolve

#### Hybrid Var:

- Linear perturbation model
- Increments from **B**<sub>c</sub> does evolve

Use Ensemble Linear Perturbation Models to updating all variables

Coupled systems

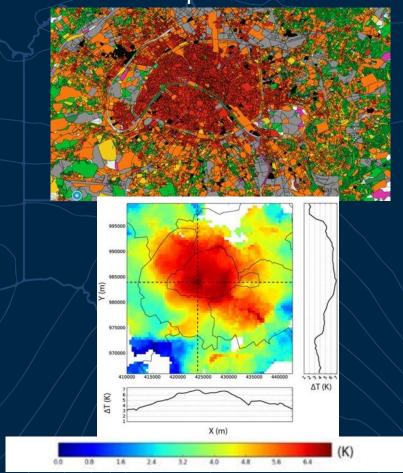
Other highly non-linear systems, e.g. urban

Poster: Nathan Eizenberg & Craig Bishop



# Urban, O(100m): Observing the urban landscape

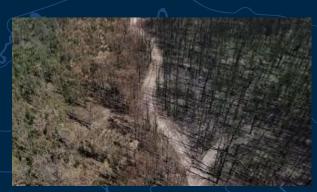
- Standard in situ observing system :
  - siting standards not appropriate
- Remote sensing :
  - Lowest level
  - footprint, safety issues, cost?
- 3<sup>rd</sup> party data :
  - Drones, Phones & Automobiles, ++
  - Coverage & cost good
  - Accessing data?
  - Obs Quality & Observation Operator
    - Possible application for AI/ML





## Land Surface

- Currently soil temperature & moisture updated
  - JULES
  - Australian Water Resources Assessment (AWRA)
- Vegetation activity ( > evapotranspiration)
   & land surface (skin) temperature
  - Effect of major fires on local conditions
  - Crop greenness



abc.net.au



abc.net.au



# More complexity = More work

- Collaboration essential
  - → Joint Environment for Data assimilation Infrastructure (JEDI)

    Combined effort across major US (and now UK) centres

- Require new tools & new skills
- Essential to stay up-to-date
  - Local developments need to be relative to latest code
  - Ease of integration from Bureau back to source code trunk
  - Software environment must support synchronized coding & testing



# Where to? More observations, used better

#### Next Few Years – introduce new infrastructure & science

- Better accounting for non-linearity: EnVar, LETLM etc.
- Greater Collaboration: JEDI
- Vegetation in land surface models

## Longer Term – start applying to new systems

- Fully Coupled DA
  - ensemble based DA with better linear model
- Urban
  - as above plus 3rd party observations (likely require Al/ML)
  - On top of the usual: satellites, radars & more satellites
  - Added importance of a high quality ensemble system.
  - New skills, including AI/ML
  - HPC environment suitable for collaboration